

**A TOOL FOR IMPLEMENTING FLOATING- POINT RELATED
APPLICATIONS USING CUSTOMIZED LANGUAGE**

LIST OF PRIOR ART

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FIELD AND BACKGROUND OF THE INVENTION:

IEEE compliance to Floating-Point hardware in microprocessors has traditionally been a challenging task to achieve. Many escape bugs, including the infamous Pentium bug, belong to the floating-point unit and reveal that the verification process in this area is still far from being optimal. The ever-growing demand for performance and time-to-market causes the verification work to become increasingly harder. So does the low tolerance for bugs on the finished product. There are many sources of problems in the implementation of the Floating-Point unit, ranging from data problems on single instructions to the correct handling of sequences of instructions in which back-to-back events challenge superscalar implementations. The roots of the complexity stem, *inter alia*, both from the interpretation of the specification (architecture) and from the peculiarities of the implementation (microarchitecture). Verification has traditionally been targeted through the simulation of test-programs [5,6]. Lately, the area of formal methods has significantly evolved, especially for the floating-point unit verification [1-4], but is still far from providing a complete answer to the problem.

Hence, in most environments, the simulation of test cases is still a major component of the verification process. Normally, for each event (test case) a customized procedure should be prepared. It is, therefore, readily appreciated that preparing numerous procedures for the many different calculation cases to test is a very labor-intensive task. In practice, then, simulation can be carried out on only a very small portion of the existing space. The rationale beyond verification by simulation is that one acquires confidence on design correctness by

running a set of test cases exercising a sufficiently large number of different cases, which, in some sense, are assumed to be a representative sample of the full space. It is inferred that the correct handling of the tested cases is a testimony for the design correctness of all cases. The difficult question is how to define such a representative set of test cases. Since both the architecture specification and the microarchitecture implementation yield a myriad of special cases, relying on pure (uniform) random test cases would be largely inefficient.

How does one know that a certain set of tests is sufficient? This question is related to the notion of coverage, i.e., to the comprehensiveness of the set related to the verification target [9-12]. Usually, coverage models are defined and the set of tests should fulfill all the existing tasks. A coverage model is a set of related cases.

For example, a common coverage model is one which requires to enumerate on all major IEEE Floating-Point types simultaneously for all operands of all FP instructions. For a given instruction with three operands, say ADD, this potentially yields a thousand (10^3) of cases to cover, assuming 10 major FP types (+/-NaNs, +/-Infinity, +/-Zero, +/-Denormal, +/- Normal). This model can be further refined by adding more FP types, such as Minimum and Maximum denormals, etc. Obviously, not all cases are possible (e.g. the addition of 2 positive denormal numbers cannot reach infinity), so that the actual number of cases is, in fact, lower than the size of the Cartesian product.

A coverage model or a set of all coverage models is typically (but not necessarily) an attempt to partition the set of all the calculation cases in such a way that the probability distribution should be similar for all

subsets. There is, thus, a need in the art to substantially reduce the drawbacks of hitherto known solutions for verifying Floating-Point standard compliance.

5 Still further, there is a need in the art to provide for an improved technique for verifying a compliance with Floating-Point standards by defining Floating-Point events of interest and, if desired, regrouping them into coverage models.

10 Still further, there is a need in the art to provide for a computer language or computer language specification which enables to define Floating-Point events of interest and, if desired, regrouping them into coverage models. Such a language can be used for various applications, e.g.
15 evaluation of coverage of tests being run on a design.

SUMMARY OF THE INVENTION:

The invention provides for an apparatus for implementing a Floating-Point related application,
20 comprising:

a tool that includes:

a receiver for receiving a list of commands in a computer language; the language defining Floating-Point events of interest in respect of at least one FP
25 instruction;

a parser for parsing the commands;

a processor configured to process at least the parsed commands for realizing the floating-point related application on the basis of said events.

30 The invention further provides for an apparatus for implementing a Floating-Point related application, comprising:

a tool that includes:

a receiver for receiving a list of commands in a computer language; the language defining Floating-Point
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events of interest and regrouping of events into at least one coverage model, in respect of at least one FP instruction; the coverage model having the form of a sequence of Floating-Point commands with constraints on
5 (i) at least one intermediate result operand of the FP instruction, and (ii) result operand of the FP instruction;

a parser for parsing the commands;

10 a processor for processing at least the parsed commands for realizing the Floating-point related application at least on the basis of said events and said at least one coverage model.

Still further, the invention provides for an apparatus for implementing a Floating-Point related
15 application, comprising:

a tool that includes:

20 a receiver for receiving a list of commands in a computer language; the language defining Floating-Point events of interest and regrouping of events into at least one coverage model, in respect of at least one FP instruction; the coverage model having the form of a sequence of Floating-Point commands with constraints on
25 (i) at least one intermediate result operand of the FP instruction, and (ii) result operand of the FP instruction; each one of said constraints is expressed as at least one set each of which defining allowable Floating-Point numbers;

a parser for parsing the commands;

30 a processor for processing at least the parsed commands for realizing at least on the basis of said events and said at least one coverage model the Floating-Point related application.

Yet further, the invention provides for a method for implementing a Floating-Point related application that
35 includes the steps of:

(i) receiving a list of commands in a computer language; the language defining Floating-Point events of interest in respect of at least one FP instruction;

- 5 (ii) parsing the commands; and
(iii) processing at least the parsed commands for realizing the floating-point related application on the basis of said events.

10 The invention provides for a method for implementing a Floating-Point related application that includes the steps of:

- 15 (i) receiving a list of commands in a computer language; the language defining Floating-Point events of interest and regrouping of events into at least one coverage model, in respect of at least one FP instruction; the coverage model having the form of a sequence of Floating-Point commands with constraints on (i) at least one intermediate result operand of the FP instruction,
20 and (ii) result operand of the FP instruction;
(ii) parsing the commands; and
(iii) processing at least the parsed commands for realizing the Floating -point related application at least on the basis of said events and said at
25 least one coverage model.

Still further, the invention provides for a method for implementing a Floating-Point related application, that includes the step of:

- 30 (i) receiving a list of commands in a computer language; the language defining Floating-Point events of interest and regrouping of events into at least one coverage model, in respect of at least one FP instruction; the coverage model having the form of a sequence of Floating-Point

09927457-081301

commands with constraints on (i) at least one intermediate result operand of the FP instruction, and (ii) result operand of the FP instruction; each one of said constraints is expressed as at least one set each of which defining allowable Floating-Point numbers;

(ii) parsing the commands; and

(iii) processing at least the parsed commands for realizing at least on the basis of said events and said at least one coverage model the Floating-point related application.

The invention further provides for a program storage device readable by machine, tangibly embodying a program of instructions executable by the machine to perform method steps for implementing a Floating-Point related application that includes the steps of :

i) receiving a list of commands in a computer language; the language defining Floating-Point events of interest in respect of at least one FP instruction;

ii) parsing the commands; and

iii) processing at least the parsed commands for realizing the floating-point related application on the basis of said events.

Still further, the invention provides for a computer program product comprising a computer useable medium having computer readable program code embodied therein for causing the computer to implement a Floating-Point related application, comprising:

computer readable program code for causing the computer to receive a list of commands in a computer language; the language defining Floating-Point events of interest in respect of at least one FP instruction;

computer readable program code for causing the computer to parse the commands; and

computer readable program code for causing the computer to process at least the parsed commands for realizing the floating-point related application on the basis of said events.

Yet further, the invention provides for a program storage device readable by machine, tangibly embodying a program of instructions executable by the machine to perform method steps for implementing a Floating-Point related application, that includes the steps of:

- (i) receiving a list of commands in a computer language; the language defining Floating-Point events of interest and regrouping of events into at least one coverage model, in respect of at least one FP instruction; the coverage model having the form of a sequence of Floating-Point commands with constraints on (i) at least one intermediate result operand of the FP instruction, and (ii) result operand of the FP instruction; each one of said constraints is expressed as at least one set each of which defining allowable Floating-Point numbers;
- (ii) parsing the commands; and
- (iii) processing at least the parsed commands for realizing at least on the basis of said events and said at least one coverage model the Floating-point related application.

Still further, the invention provides for a computer program product comprising a computer useable medium having computer readable program code embodied therein for causing the computer to implement a Floating-Point related application, comprising:

computer readable program code for causing the computer to receive a list of commands in a computer language; the language defining Floating-Point events of interest and regrouping of events into at least one

09927457-081301

coverage model, in respect of at least one FP instruction;
the coverage model having the form of a sequence of
Floating-Point commands with constraints on (i) at least
one intermediate result operand of the FP instruction, and
5 (ii) result operand of the FP instruction; each one of
said constraints is expressed as at least one set each of
which defining allowable Floating-Point numbers;

computer readable program code for causing the
computer to parse the commands; and

10 computer readable program code for causing the
computer to process at least the parsed commands for
realizing at least on the basis of said events and said
at least one coverage model the Floating-point related
application.

15 The invention provides for a program storage device
readable by machine, tangibly embodying a program of
instructions executable by the machine to perform method
steps for implementing a Floating-Point related
application, that includes the steps of:

20 (i) receiving a list of commands in a computer
language; the language defining Floating-Point
events of interest and regrouping of events into
at least one coverage model, in respect of at
least one FP instruction; the coverage model
25 having the form of a sequence of Floating-Point
commands with constraints on (i) at least one
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Floating-Point numbers;

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09927457, 081301

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computer readable program code for causing the computer to receive a list of commands in a computer language; the language defining Floating-Point events of interest and regrouping of events into at least one coverage model, in respect of at least one FP instruction; the coverage model having the form of a sequence of Floating-Point commands with constraints on (i) at least one intermediate result operand of the FP instruction, and (ii) result operand of the FP instruction; each one of said constraints is expressed as at least one set each of which defining allowable Floating-Point numbers;

computer readable program code for causing the computer to parse the commands; and

computer readable program code for causing the computer to process at least the parsed commands for realizing at least on the basis of said events and said at least one coverage model the Floating-Point related application.

BRIEF DESCRIPTION OF THE DRAWINGS

In order to understand the invention and to see how it may be carried out in practice, a preferred embodiment will now be described, by way of non-limiting example only, with reference to the accompanying drawings, in which:

Fig. 1 is a generalized schematic illustration of a tool for implementing Floating-Point (FP) related

applications in accordance with one embodiment of the invention;

Fig. 2 is a generalized schematic illustration of an FP parser and an exemplary description of a customized language in accordance with one embodiment of the invention;

Fig. 3 illustrates a specific example of a coverage model;

Fig. 4 is a generalized schematic illustration of the tool of Fig. 1 serving for generation of verification FP vectors, in accordance with one embodiment of the invention;

Fig. 5 is a schematic illustration of the generator of Fig. 4, in accordance with one embodiment of the invention; and

Fig. 6 is a generalized schematic illustration of the tool of Fig. 1 serving for evaluation of coverage of tests being run on a design, in accordance with one embodiment of the invention.

DETAILED DESCRIPTION OF THE INVENTION

Attention is first directed to Fig. 1, illustrating a generalized schematic illustration of a tool, (10), for implementing Floating-Point (FP) related applications, in accordance with one embodiment of the invention. The tool includes a parser module (11) configured to receive commands in a customized language (12), generate parsed commands and feed the so-parsed commands to a processor (13) that processes the commands for realizing a pre-defined (FP) related application. The invention is not bound by the specified tool configuration. The tool or portions thereof are realized in software, hardware, customized chip, or a combination thereof, all as required and appropriate.

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Turning now to Fig. 2, there is shown a generalized schematic illustration of an FP parser (20) and an exemplary description of a customized language utilizing the following commands: Range, Mask, Set/Reset No-of-Bits, Set/Reset Continuous-Bit-Long; Relative Values of FP numbers and Set operations (OR, NOT, AND) (21), in accordance with one embodiment of the invention. The specific syntax is not given, seeing that the actual realization is generally known per se.

By one aspect of the invention, the language captures and defining an interesting Floating-Point event or events, and one (or more) groups of the events that constitute a coverage model(s).

By one embodiment, a coverage model is defined by specifying a set of different constraints to be fulfilled, each constraint corresponding to a particular task targeted by the coverage model. More precisely, a coverage model has the form of a sequence of FP commands, with sets of constraints on at least one of the following: (i) at least one intermediate result operand and (ii) result operand. If desired, the constraints may be imposed also on one or more of the input operands. The general outlook of a single instruction constraint may be in the following form:

$$\text{Fpinst}(\text{Op1 in Pattern1})(\text{Op2 in Pattern2})(\text{IntRes in Pattern3})(\text{Res in Pattern4}) \quad (\text{Eq.1}),$$

where Fpinst is a generic Floating-Point instruction with two input operands (Op1 and Op2), one intermediate result (IntRes) operand, and a result (Res) operand. The case of two input operands and a single intermediate result operand is used here for simplicity of notation, but of course, generalization to any number of such parameters is also applicable. By one embodiment, each one of said constraints is expressed as a set of allowable

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Floating-Point numbers. For convenience of description, consider a Pattern as a construct representing a logical OR among sets of FP numbers. The sets serve as constraints defining (in fact limiting) the allowable FP numbers for each term of (Eq. 1). Patterns have the general following form:

$$\text{Pattern} = \text{Set1 OR Set2 OR...OR SetN} \quad (\text{Eq. 2}),$$

where each Set is a set of FP numbers. Each task of the coverage model corresponds to a specific selection of Set for each Pattern. Hence, covering the task is reduced to selecting a data vector where each individual data belongs to the corresponding selected Set. Thus, the number of different tasks engendered by such a single instruction is the multiplication of the number of Sets for each participating Pattern. The number of tasks for a sequence is obtained by multiplying the number of tasks of each individual instruction. It should be noted that the terms tasks and patterns are used interchangeably.

Whereas in the latter example the input operands, intermediate result operand and the result operand are all subject to pattern constraints, the invention is by no means bound by this example. Thus, by a modified embodiment, the intermediate result operand is subject to a pattern constraint and/or the result operand is subject to a pattern constraint. If desired, one or more of the input operands may also be subject to pattern constraint. The utilization of the pattern constraints will be exemplified below with reference to Fig. 3.

It should be noted that not necessarily all the FP number parts are limited (e.g. Mantissa and Exponent, constituting, each, a part of the FP number). Thus, if desired, only selected constituent(s) is (are) subject to

the limitation, e.g. only the Mantissa or only the Exponent.

In accordance with one embodiment, the input is described in a language with set based constraints that facilitate the definition of different sets of FP numbers. This serves to conveniently define desired constraints posed by, say a verification plan's tasks. There follows now a description of a few possible commands in a set based language which facilitate the definitions of the specified constraints.

- Ranges and masks : Separate range constraints are possible on the Exponent and Mantissa. A mask is represented by an FP number where some bits are X (Don't care) while the others are regular 0's and 1's.
- Set/Reset No-of-Bits: the ability to specify the number of bits equal to 1 (or 0) within any given field of the FP number. Exact, MIN and MAX are given (for example: at least 1 bit set in bits 61-63).
- Set/Reset Continuous-Bit-Long: Ability to specify length of continuous stream of 1's or 0's. As before, Exact, MIN and MAX are given for any field without overlapping between fields, and without crossing the Mantissa-Exponent border. For example, a number with a continuous stream of at least 45 1's in its mantissa.
- Relative Values of FP numbers: Specifying a Set for which the selected value should be a function of the value selected for another operand (usage of symbol). By one embodiment, + and - are sufficient, but by modified embodiment, the language can support additional operators. These operations have to be understood as the

distance in terms of representable numbers. The symbols must be enabled on any field of the number. (Example: exponent at a distance of at most 2 from the exponent selected for the previous operand).

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- Sets operations (Intersection, union, complement, of same and different Set types).

10 The specified commands can be applied to one or more of the FP operands, i.e. anyone of the input operands, intermediate result operand(s), and final result operand.

15 It should be noted that the Set-Based language embodiment is by no means bound by this particular list of commands. Accordingly, one or more of the specified commands may be modified and/or deleted. Others may be added, all as required and appropriate, depending upon the particular application.

20 In general, any architecture resource which may influence FP instruction's results should also be defined. For example, for IEEE standard architecture, this bounds to Rounding Modes (e.g. +infinity; -infinity; 0 or nearest) and Enabled Flags, and they will therefore be part of the language. Thus, for example, coverage models
25 defined by sequences of single instruction constraints (Eq.1) are complemented by the definition of the specified attributes. The attributes are enabled, disabled or Don't care. Using 0,1 and Don't care states with the ability to OR between these settings facilitates definition of
30 coverage model(s) that encompass on several or all the values of such attributes. The use of the supplemental attributes (e.g. rounding models and enabled flags) will also be exemplified with reference to Fig. 3 below.

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The set based language embodiment is useful for various applications including, but not limited to, FP verification plans. It enables to capture a wide scope of Floating-Point events. Even unexpected corner cases, often stemming from complex microarchitecture implementation, are expressible through a set based language.

For a better understanding, there follows now a short description that exemplifies the usage of the specified commands in few typical, yet not exclusive, scenarios of verification plan application.

- Range & Masks: certain values are critical, and it is important to be able to target both the neighborhood of these values (range) and numbers at a distance of a few bits (Masks). Moreover, to check correct rounding, only some bits of the intermediate results are relevant, while others can be random (Don't care).
- Set/Reset Continuous-Bit-Long: It is often the case that numbers exhibiting extraordinary sequences of 1's and 0's are being handled in a specific way (to gain performance) in the microarchitecture. For example, a number with a very long sequence of 1's (as in the Pentium bugs and in several PowerPC 630 bugs).
- Relative Values of FP numbers: These relate between exponents of operands, say input operands. Consider for example, FADD between two input FP operands. When exponents are too far apart (which accounts for the vast majority of cases), the addition is reduced to a trivial calculation, (i.e. the result more or less equals to the larger input operand). Thus, for example FADD (2^{512} , 2^{400}) after rounding equals about 2^{512} , i.e. the value of the larger operand. It is therefore desired

to pose constraints on the exponent values of the input operands to be near (rather than far apart), so as to give rise to a result operand that is different than any of the input operands. This would better test the *FADD* instruction. This constraint can be easily realized by utilizing the *Relative Values of FP numbers* command . By another example, the *Relative Values of FP numbers* command can also be used to relate between an input operand and the result operand.

The utilization of Set-based language commands for verification plan purposes is, of course, not bound by the specified example. It would be noted, generally, that the set based language provides a powerful mechanism to pinpoint the targeted areas.

Another non-limiting example of utilizing the set-base language for verification plan application is by imposing constraint on the input and result operands (including intermediate result) using, say, the range command. This allows to define an event such as an overflow (intermediate result constraint) with one of the operands being a *denormal* number (input operand constraint).

By an alternative non-limiting embodiment, the tool that utilizes the language can be utilized for realizing coverage models, e.g. by regrouping events. Consider, for example, the set-based language that utilizes the specified command list. Fig. 3 illustrates an *FADD* instruction having *OP1* and *OP2* input operands, intermediate result operand, and an output operand (*31* to *34*, respectively). The constraints on the FP instruction comply with the notation of equation 1 above. The constraints for, say, the input operand *OP1* (*31*) and result operand (*34*) limit the number of allowable FP numbers for each operand and can be represented, for

convenience, in a form of a pattern (see Eq. 2). Thus, for OP1 (31), the allowable FP numbers being a logical OR among the following four sets: *+Norm*, *-Norm*, *+Inf* and *-Inf* (31^1 to 31^4 respectively), where each set is implemented using the specified *range* command. In a similar manner, the allowable FP numbers for the result operand (34) is limited by a logical OR among the two sets *+Norm*, *-Norm*. The second input operand (32) and the intermediate result operand (33) are not subject, by this example, to any constraint. Whereas the latter example is confined to only the *+ Norm* and *+ Inf* sets, the invention is, of course, not bound by this specific example and accordingly other sets of FP numbers (such as *+Denorm*, *+Zero*, *+Nans*; *+Max/Min Norm/Denorm*, in accordance with the IEEE standard) may be used all as required and appropriate. Each task of a coverage model corresponds to a selection of a specific set for each pattern (for those operands that are subject to pattern constraints, e.g. OP1 and result operands in Fig. 3). The FP numbers that are generated fall in the so selected sets. Thus, for a given task the *+Norm* set is selected for OP1 and *-Norm* set is selected for the result operand. The generated FP number for OP1 falls in the range of *+Norm* and the generated FP number for the result operand falls in the range of *-Norm*. There is no limit (i.e. set constraint) for the FP numbers of OP2 and the intermediate result as long as they meet the provision of the FADD instruction.

The coverage model for the FP instruction (say the specified FADD) encompasses all the possible tasks, such that for each task a different set combination is selected. (in the example of Fig. 3, there are 8 different tasks, i.e. multiplying four sets of the OP1 pattern by two sets of the result operand pattern.

As specified above, it is required to take into account the architecture resources which may influence the

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5 result of the FP instruction, such as the rounding mode
(e.g. +infinity, -infinity 0, or nearest), flag register
(e.g. overflow state, underflow state) and possibly
others. By one embodiment, selected attributes are
assigned, each, with "1" (enable), 0 (disable) or Don't
care with the ability to OR between these settings in a
similar manner as OR between sets in the specified pattern
representation, thereby providing a comprehensive coverage
model which not only embraces the selection of desired FP
10 numbers, but also takes into account selected values of
the attributes which represent the machine state. In the
example of Fig. 3, the FADD instruction is tested (with FP
numbers that are selected as explained in detail above)
for both *enable* and *disable* states of the overflow flag *OF*
15 (35) and for both 0 and *nearest* rounding modes (36).

There follows now a specific example with reference
to Fig. 4, in which the tool is used in an application for
generating test vectors (41) for Floating-Point
verification of microprocessors. The test vectors are
20 generated according to a desired type of Floating-Point
event(s) or/and coverage model(s) as defined by the input
commands of the set-based language (42). To this end, the
FP number generator (43) generates test vectors (41)
satisfying the input constraints (42).

25 Turning now to Fig. 5, there is shown one possible
realization of the generator (43). As may be recalled, in
accordance with an embodiment of the invention, the
language enables constraints on the input, intermediate
result and result operands, and even enables to define
30 these constraints simultaneously. The test generator (43)
in accordance with Fig. 5, operates as follows: it solves
only the input operand constraints (51), and in case the
solution does not match (52) the other (i.e. result and/or
intermediate result operands) constraints, it tries again

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(53) until it either succeeds (54) or a time limit elapses (55). Solving the input is implemented by choosing a single element from a set. Solving the input constraints does not include being knowledgeable of the command semantics, and that is where the complexity starts. In order to alleviate this complexity, a reiterating probabilistic-attempt technique is used. The invention is, of course, not bound by this specific generator, and by an alternative embodiment, another generator may be used, e.g. a generator that solves also the result/intermediate result constraints.

Another non-limiting application of the tool of the invention is illustrated in Fig. 6. This application concerns evaluating the coverage of tests being run on a design. The source of the tests is of no importance. Commonly, there are available suites of tests coming from multiple sources (test generators, manually written tests, tests coming from previous similar designs, commercial suite of tests, etc.). Now, a very important question is raised, i.e. how does one know that a certain test is done? This is an issue related to coverage, which is a measurement of what has actually been tested related to the target. Since, in accordance with the invention, the test-plan can be formally written via a language of the kind specified, it can serve as the coverage reference for an appropriate coverage tool.

In accordance with another example, the tool and the associated language as described above can serve as the means to write the Floating- Point oriented Verification Plan.

Typically, the verification process of a microprocessor starts with the establishment of a Verification Plan (VP). This document includes a comprehensive description of all the verification goals. The VP should be composed from a deep understanding of the

09927457-081301

architecture, and from the known peculiarities of the microarchitecture implementation. Available verification means (e.g., existing tests, test generators, etc.), should not be taken into account, as they might interfere with the desired scope of the document. As the design evolves and while the microarchitecture is being refined and modified, the VP should be updated to reflect additional microarchitecture knowledge. A VP should also be incremented to reflect new insight brought by bug discovery, especially when the bug was found by chance and the VP did not previously cover the event leading to the bug.

Therefore, the VP is a dynamic document reflecting the present state of the design and the verification knowledge acquired.

In short, a Floating-Point VP is composed of a set of Floating-Point events, whose verification is assumed to provide a high-level of confidence on the design correctness.

The language commonly used to define these events is plain English. Beyond the standard problems of ambiguity due to the fact that English is not a formal language, the coverage models typically requested are complex and lengthy to write up. Less tangibly, but not of less importance, is the fact that not having a dedicated language practically limits the scope and comprehensiveness of the targeted set of events.

The language of the invention provides a powerful tool for composing VP, oriented towards the data-path of the Floating-Point Unit. It provides the natural constructs to capture FP complexity, define related events and coverage models, and thus enable to define the VP in a concise, and yet comprehensive manner.

In the method claims that follow, alphabetic characters used to designate claim steps are provided for

convenience only and do not imply any particular order of performing the steps.

It will also be understood that the system according to the invention may be a suitably programmed computer.

5 Likewise, the invention contemplates a computer program being readable by a computer for executing the method of the invention. The invention further contemplates a machine-readable memory tangibly embodying a program of instructions executable by the machine for executing the
10 method of the invention.

The present invention has been described with a certain degree of particularity, but various alterations and modifications can be carried out without departing from the scope of the following Claims:

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